An aerial photograph of a mountainous region. A large, dark blue lake is the central focus, surrounded by a dense network of smaller rivers and streams. The terrain is rugged, with green and brownish-yellow patches indicating vegetation and rocky areas. The overall scene is a natural, mountainous landscape.

# **BAIKAL-GVD**

## **Prototyping Phase – 2013**

**Zh.-A. Dzhilkibaev, INR (Moscow),  
for the Baikal Collaboration  
MANTS, Garching, 14-15  
October, 2013**

# Gton Volume Detector (Lake Baikal)

10368 photo-sensors at 216 strings  
 27 subarrays (clusters with 8 strings)  
 String: 4 sections, 48 photo-sensors  
 Active depths: 600 – 1300 m

To Shore: 4 – 6 km

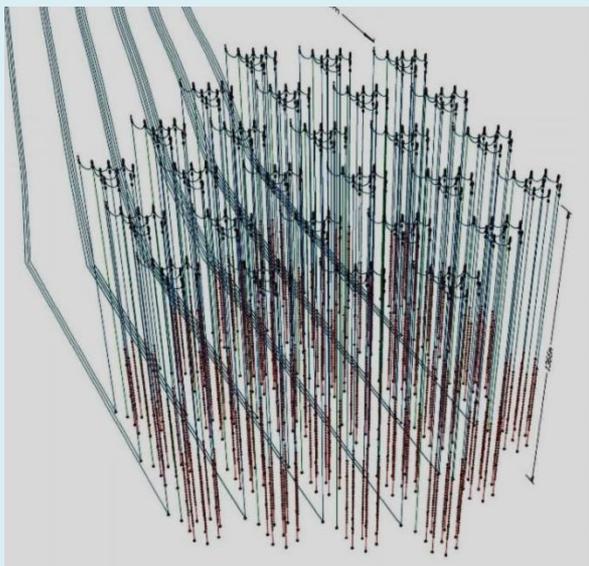
**Instrumented water volume**

$$V = 1.5 \text{ km}^3 \quad S = 2 \text{ km}^2$$

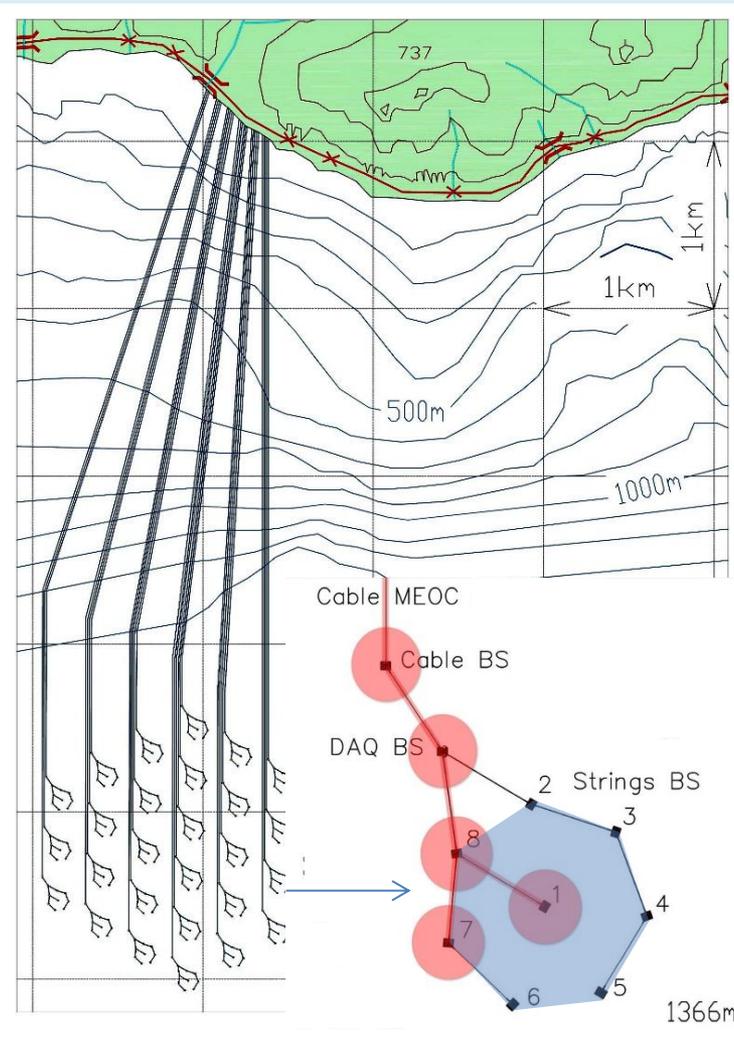
**Angular resolution**

Muons: 0.25 degree

Showers: 3.5-5.5 degree

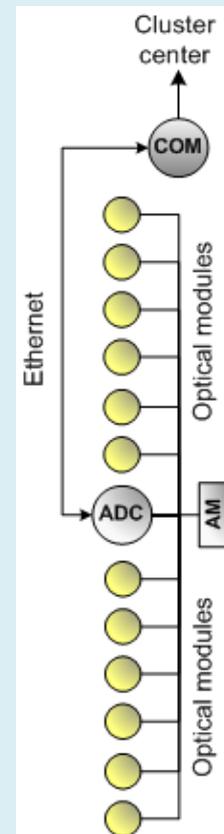


GVD array

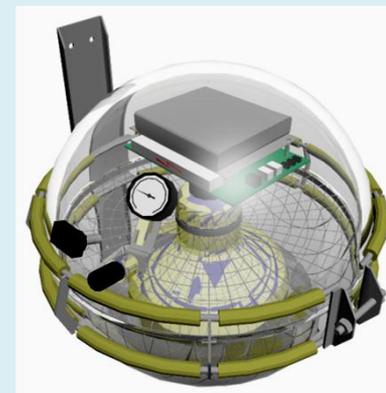


1<sup>st</sup> GVD cluster: 8 strings

● - Installed strings and cable stations

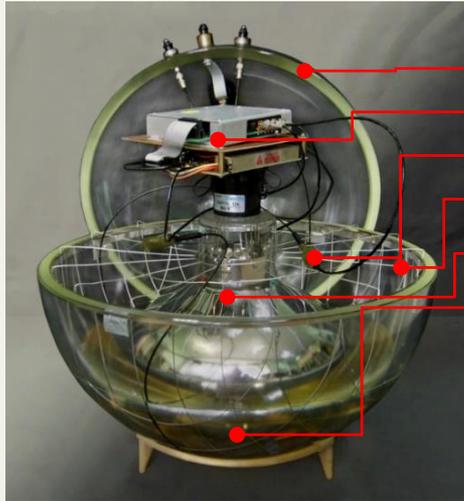


Section: basic detection unit



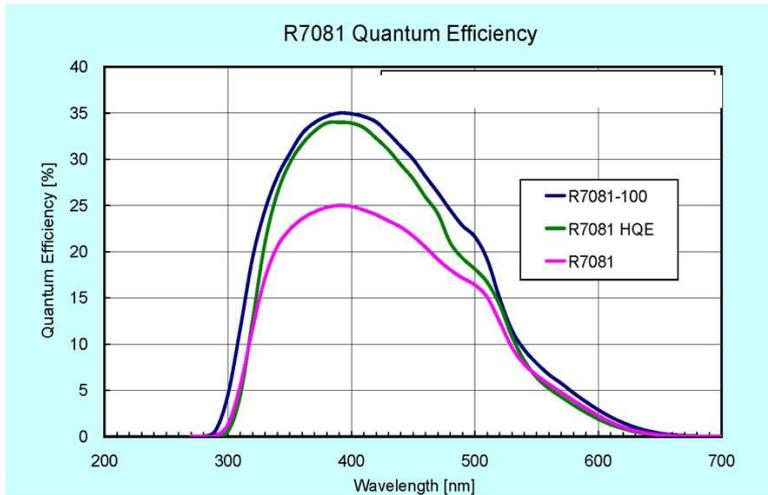
Optical module

# Optical module (OM)

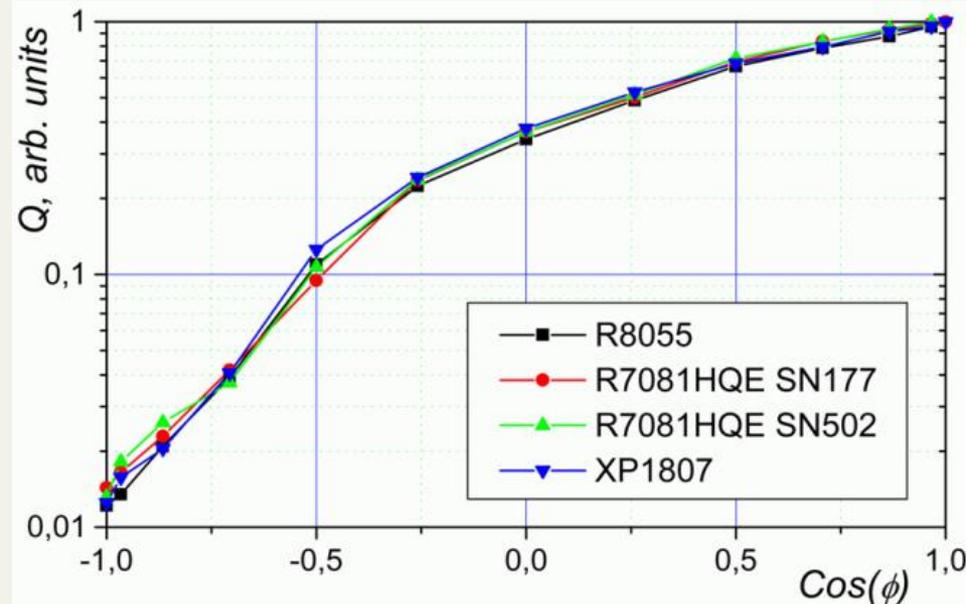


- Glass pressure-resistant sphere VITROVEX (17")
- OM electronics: amplifier, HV DC-DC, RS485 controller
- 2 on-board LED flashers:  $1 \dots 10^8$  pe., 470 nm, 5 ns
- Mu-metal cage
- PMT R7081HQE :  $D=10''$ ,  $\sim 0.35QE$**
- Elastic gel

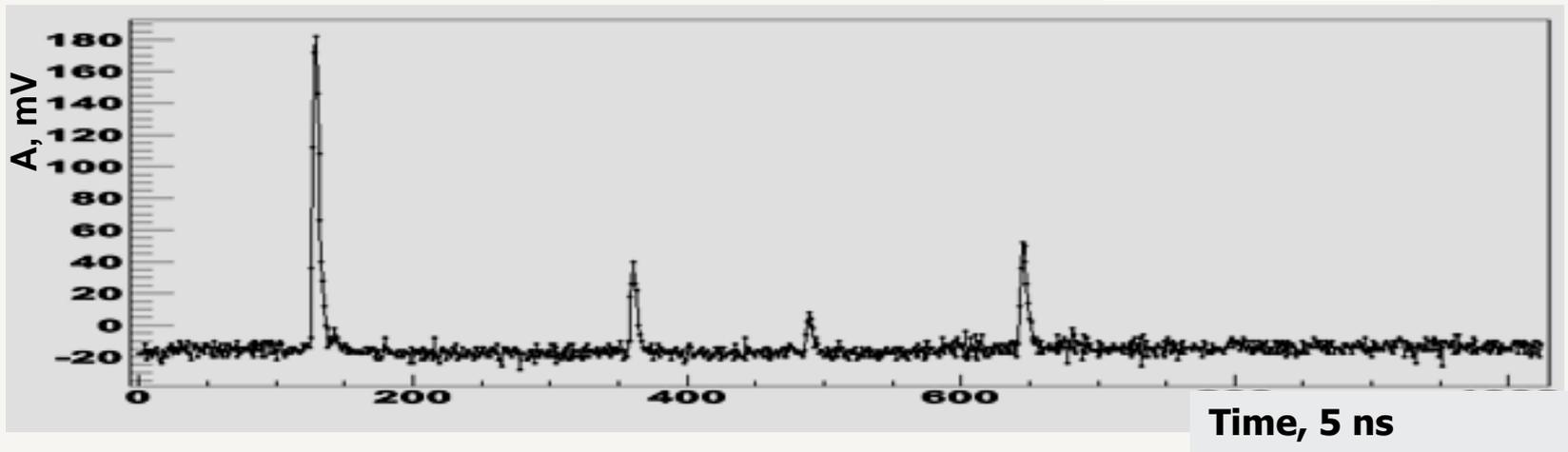
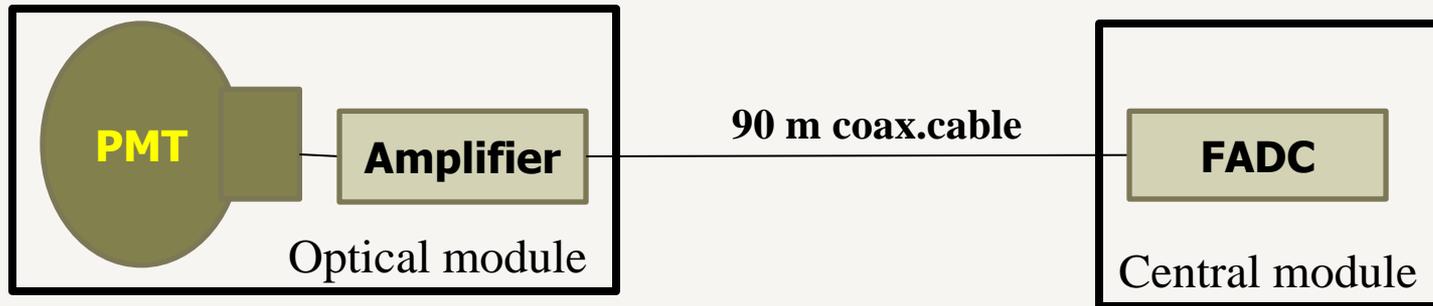
## Quantum efficiency



## Angular sensitivity



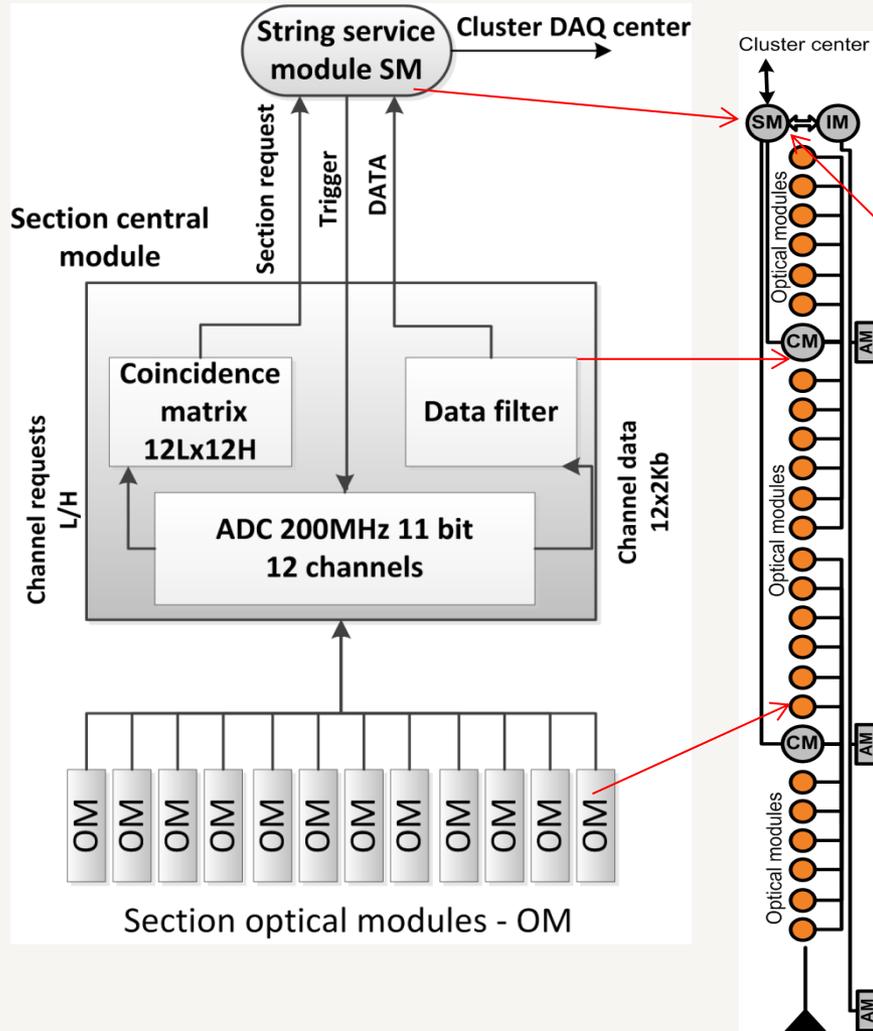
# Measuring channel



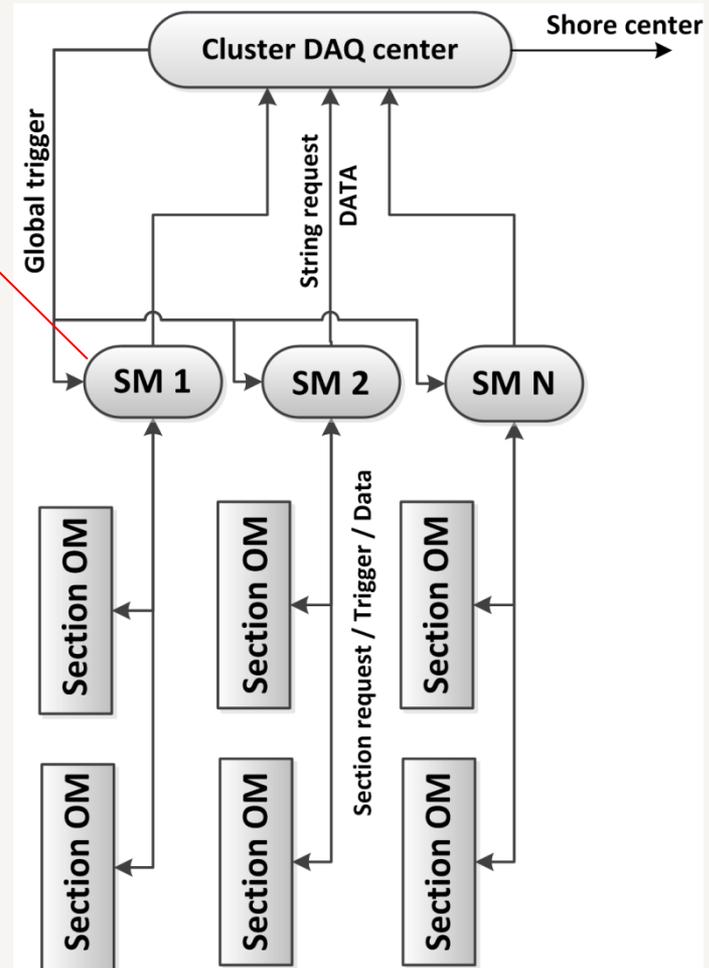
- Nominal PMT gain  $1 \times 10^7$  (PMT voltage 1250 – 1650 V)
- Amplifier,  $k_{\text{amp}}=10$ ;
- Pulse width  $\sim 20$  ns
- ADC: 11 bit 200 MHz FADC (5 ns time bin);
- Waveform information is collected for a programmable interval (up to 30 mks)
- Linearity range: 1 – 100 p.e.;

# Triggering and Data Transmission

## SECTION



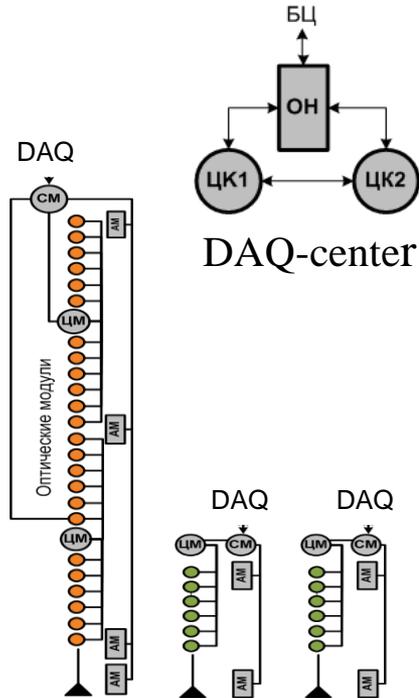
## CLUSTER



# Engineering arrays (2012-2015)

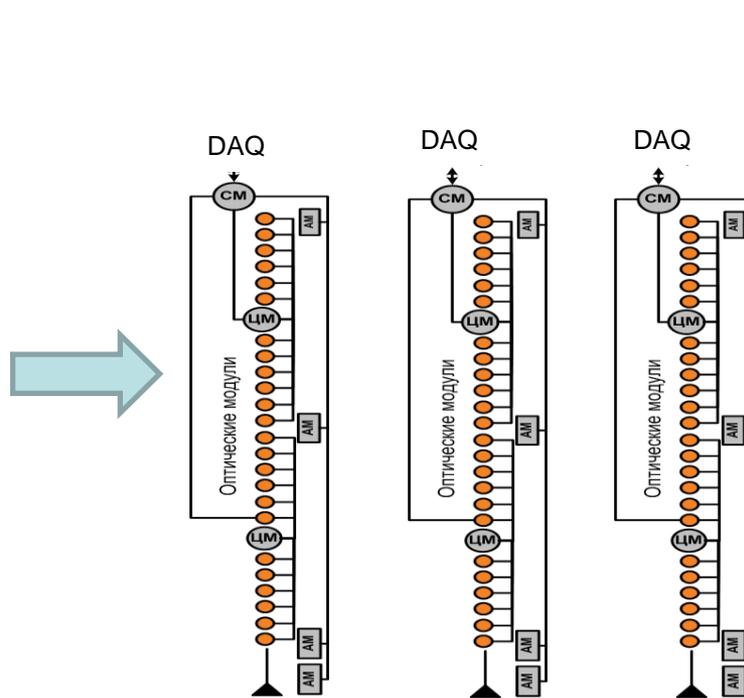
April 2012

3 strings, first full-scale  
GVD string (24 OMs)



April 2013

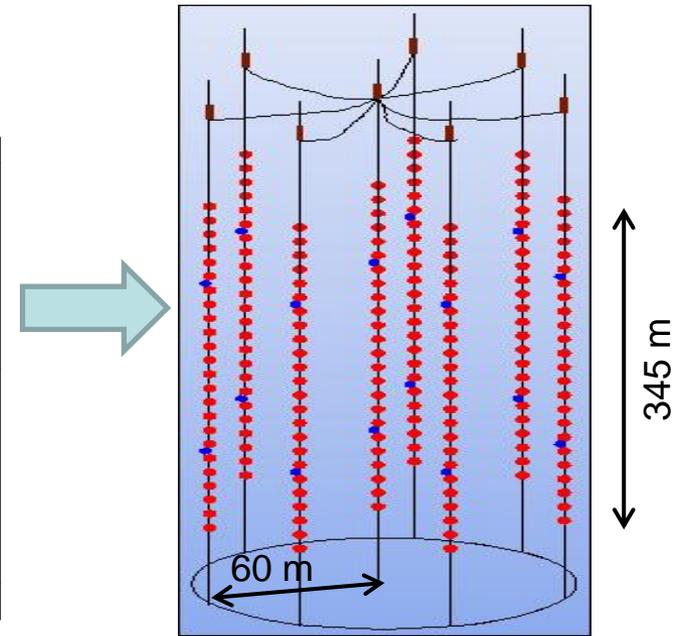
3 full-scale strings (72 OMs),  
update of section electronics



$\sim 10^6 \text{ m}^3$  instrumented volume

2014-2015

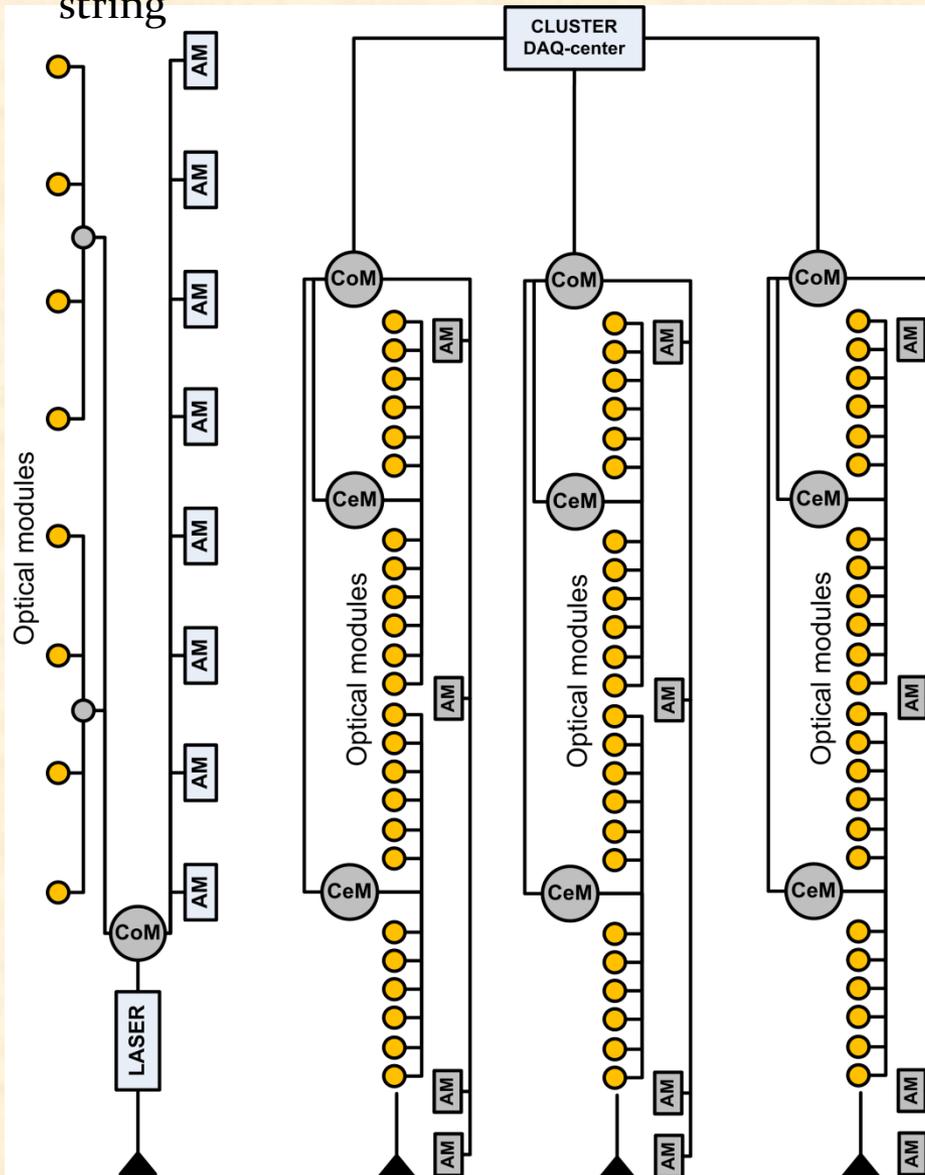
Demonstration Cluster  
8 strings  
(ANTARES-scale array)



$\sim 4 \times 10^6 \text{ m}^3$

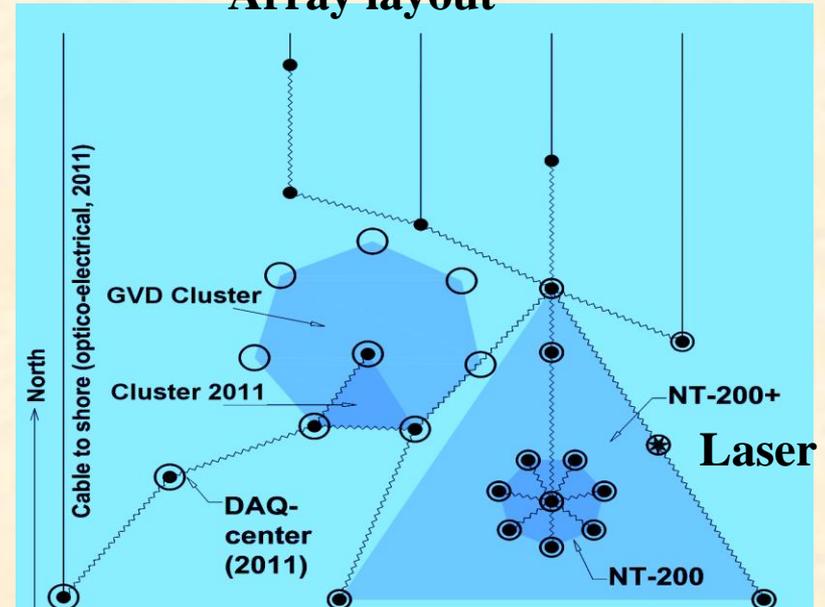
# The first stage of Demonstration Cluster

Instrumentation  
string

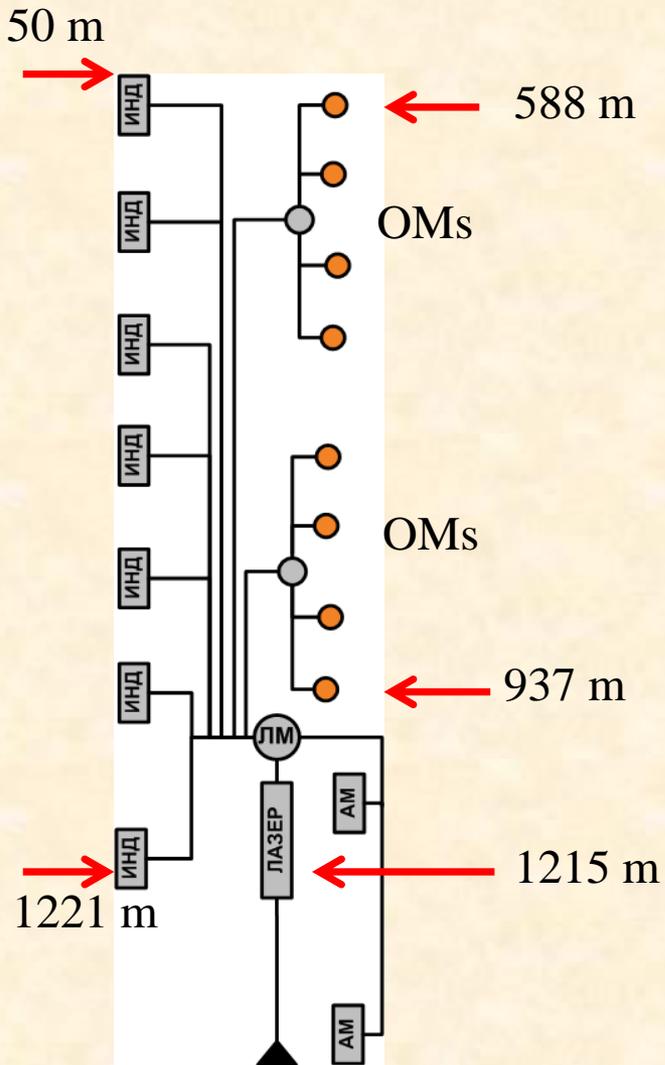


- 72 OMs (R7081HQE, R7081-100)
- 3 Strings (24 OMs / Str.)
- 6 Sections (12 OMs / Sec.)
- OMs vertical spacing – 15 m
- String length - 345 m
- Distances between strings – 40m
- 12 Acoustic Modems (4 AM / Str.)
- DAQ-Center
- Instrumentation string
- Cable to shore

## Array layout



# Instrumentation string

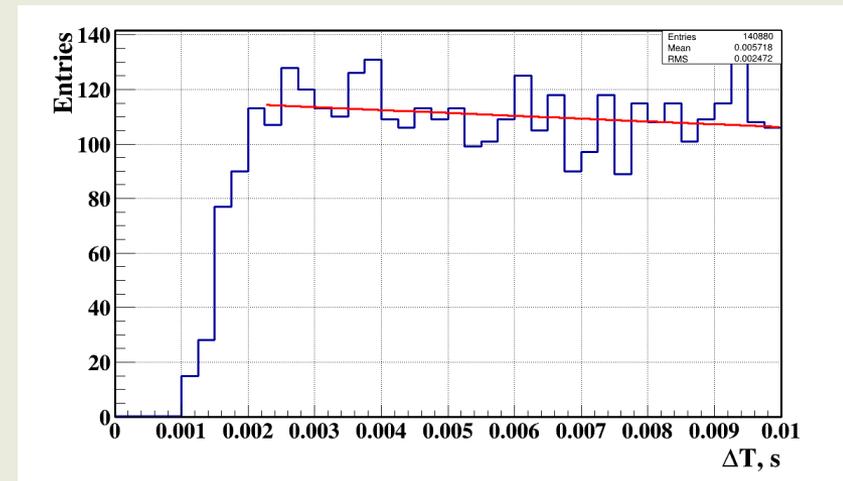
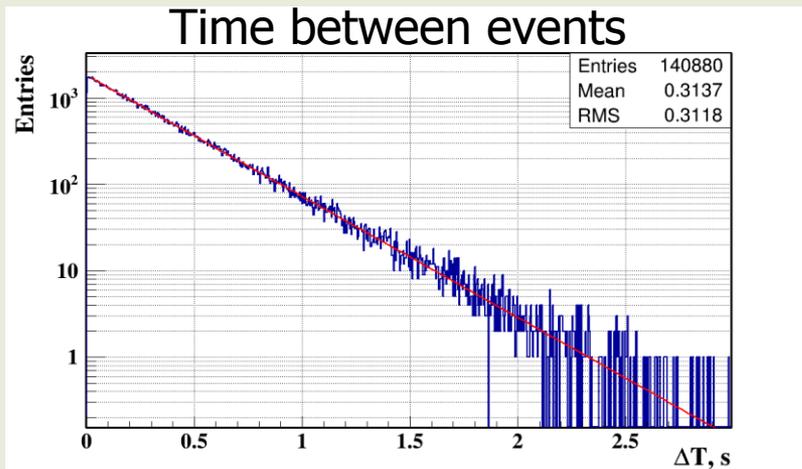
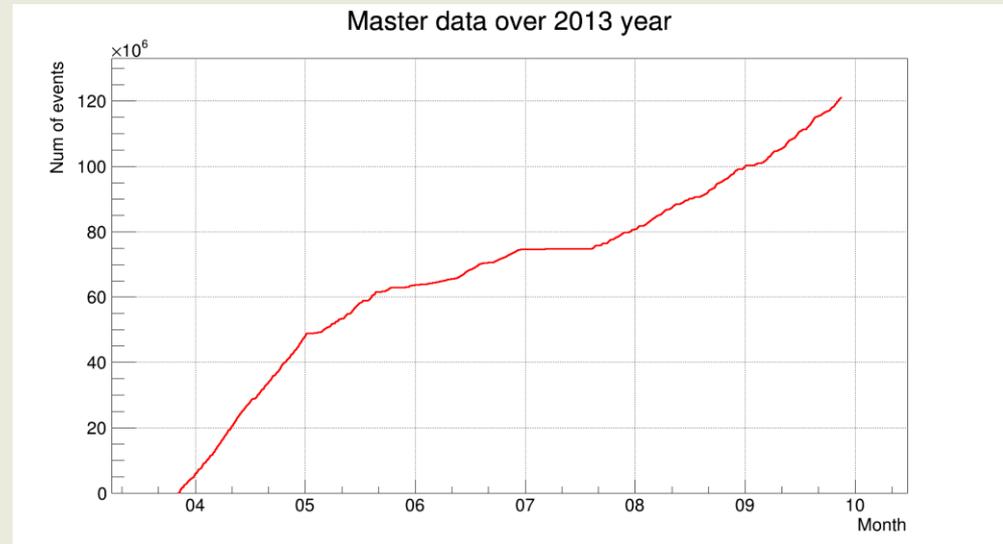


- 8 OMs at 588–937 m depths for light background monitoring
- 10 acoustic sensors at 75-1220 m depths for string shape behaviour monitoring
- 2 Acoustic modems (EvoLogics)
- Laser based calibration light source

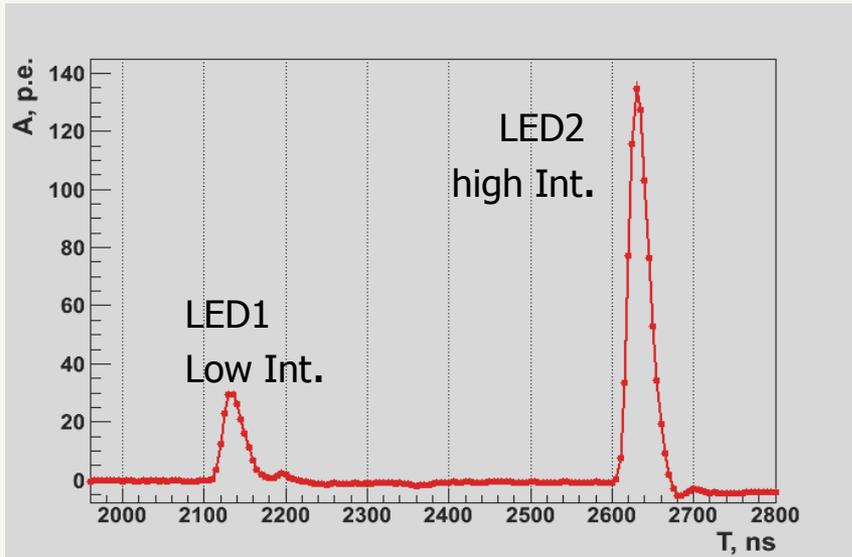
# Operational statistics

10 April – 7 October - 182 days

- Data taking: 131 days
- Efficiency: 71.8%
- Total: 458 Runs
- Data : 120930710 events
- Monitoring: 687269 events



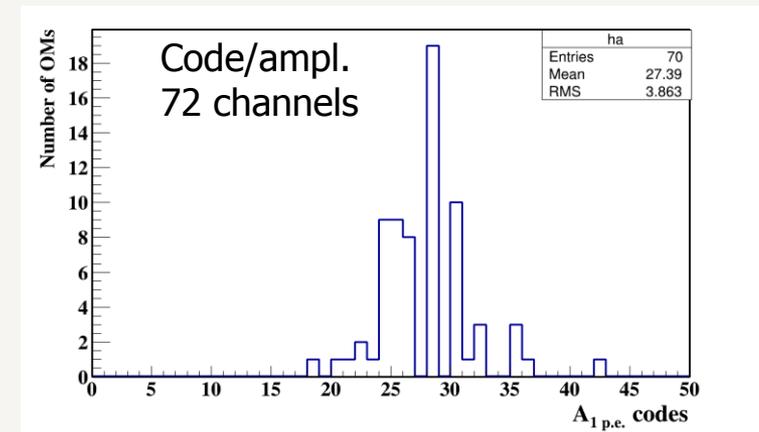
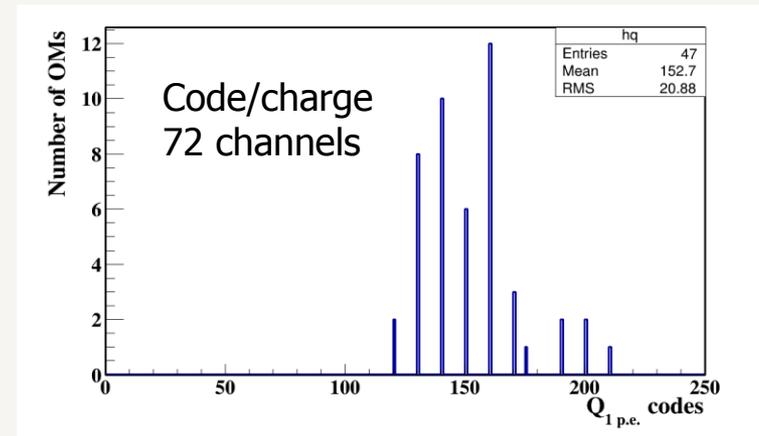
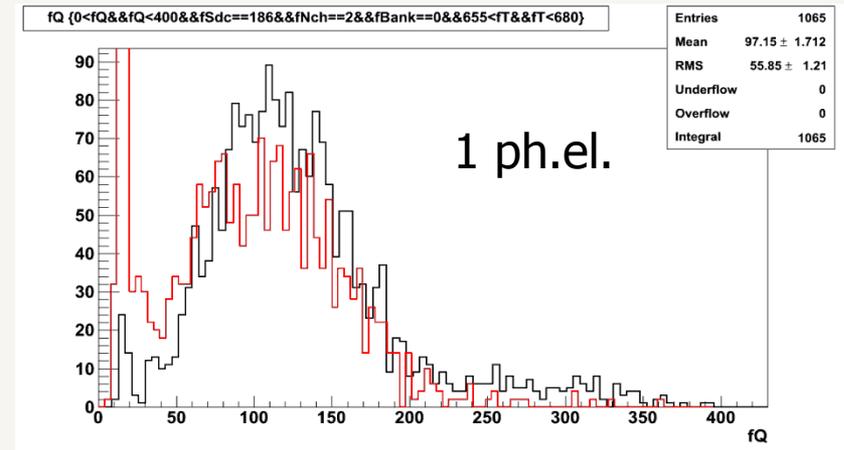
# Amplitude calibration



Calibration methods:

1 – two LEDs with high and low (10% OM detection probability) intensities

2 – analysis of noise pulses

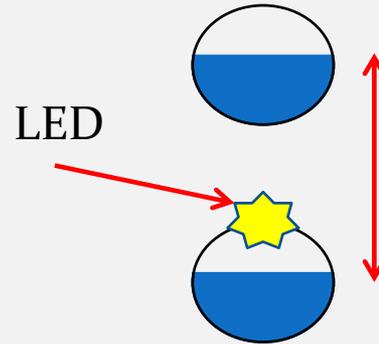
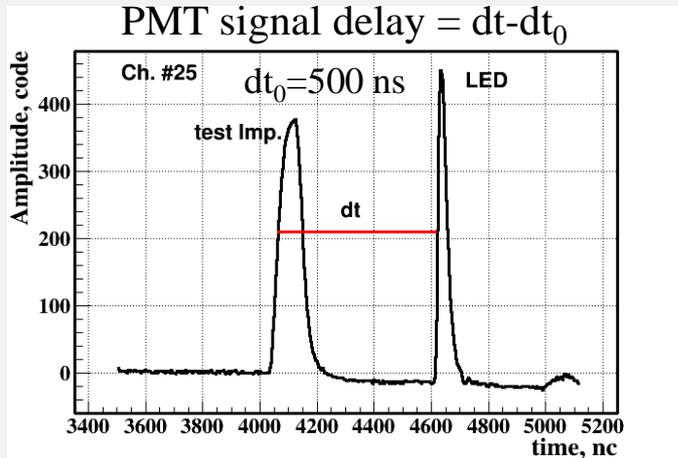
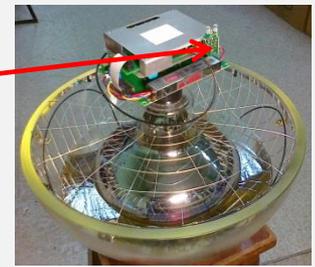


# Time calibration – two methods

Measurement of signal delay  
of each channel

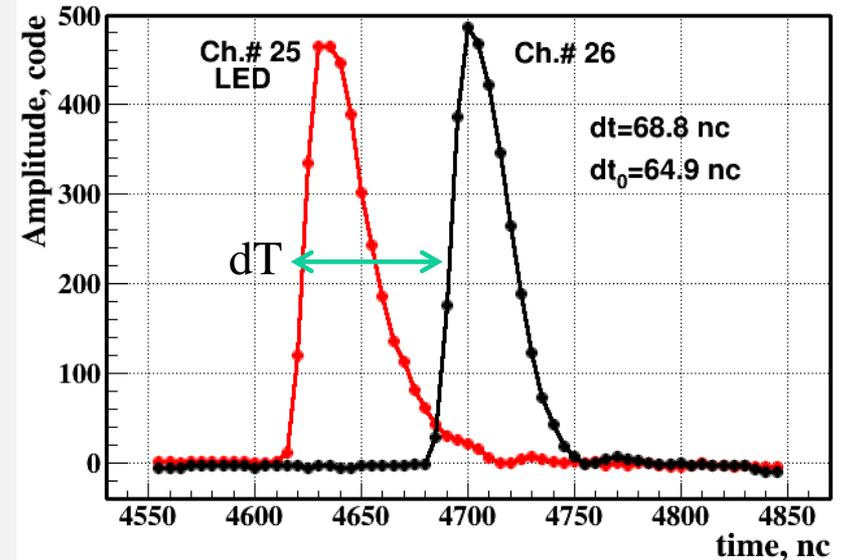
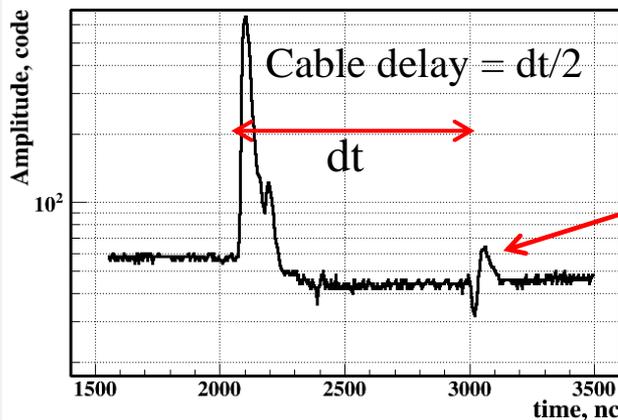
Time difference  
of two channels

two LEDs



15 m- distance between OMs  
 $dt_0 = 64.9 \text{ ns}$  – expected  
time difference

Signal delay in cable (~90 m)  
is measured in lab.



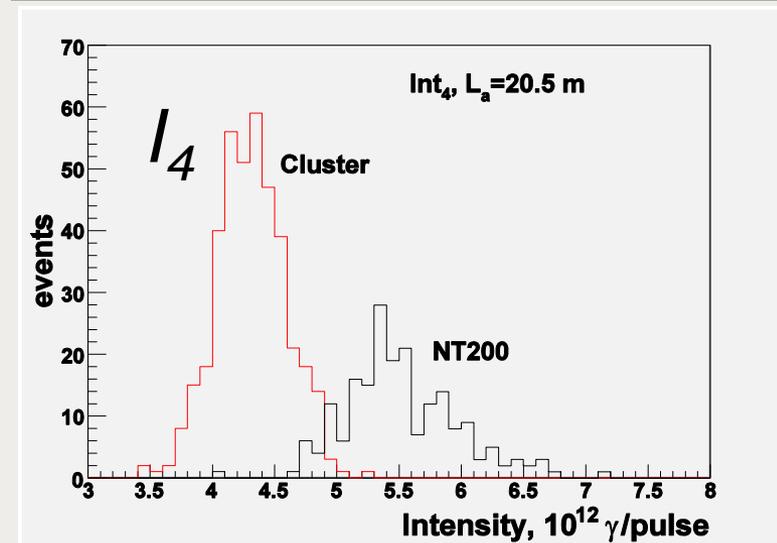
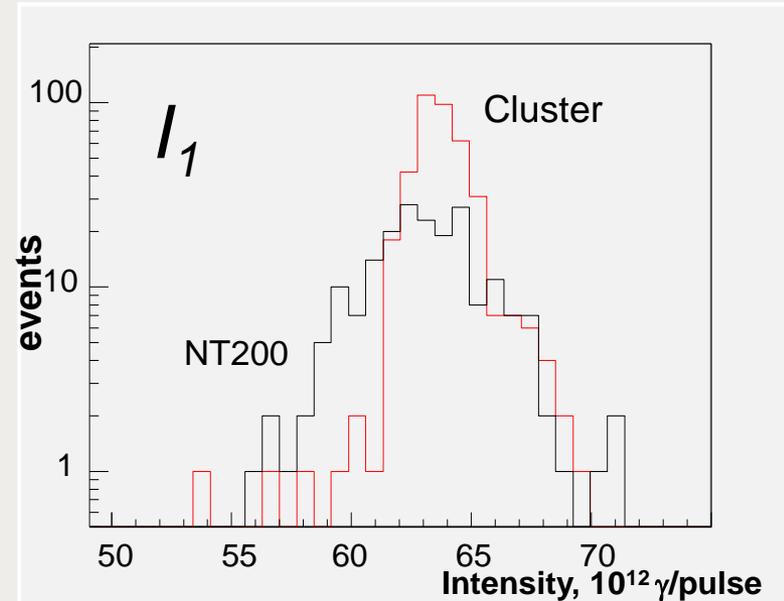
# Laser intensity reconstruction (2011)

## External calibration laser:

- 480 nm light pulses;
- Five fixed intensities:  $\sim 10^{12} - 6 \times 10^{13} \gamma / pulse$   
( $\sim 10$  PeV – 600 PeV shower energy)
- Distances: 110 – 180 m.

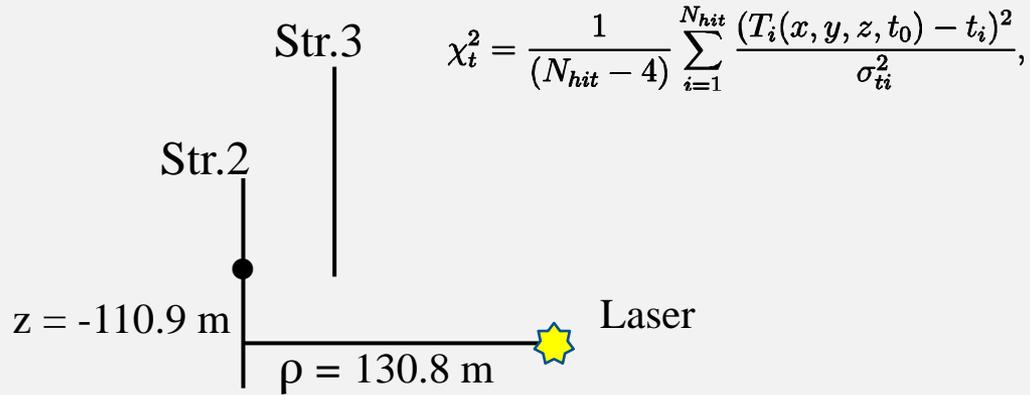
## Average values of reconstructed intensities for five light source output series

$I, 10^{12} \gamma / pulse$	$I_1$	$I_2$	$I_3$	$I_4$	$I_5$
Cluster	64	27	9.7	4.3	2.4
NT200	63	28	10.4	5.5	3.8

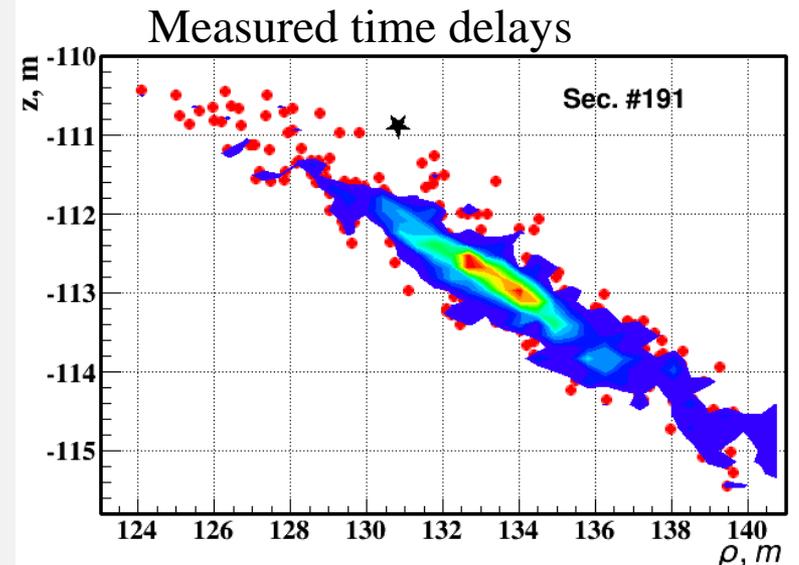
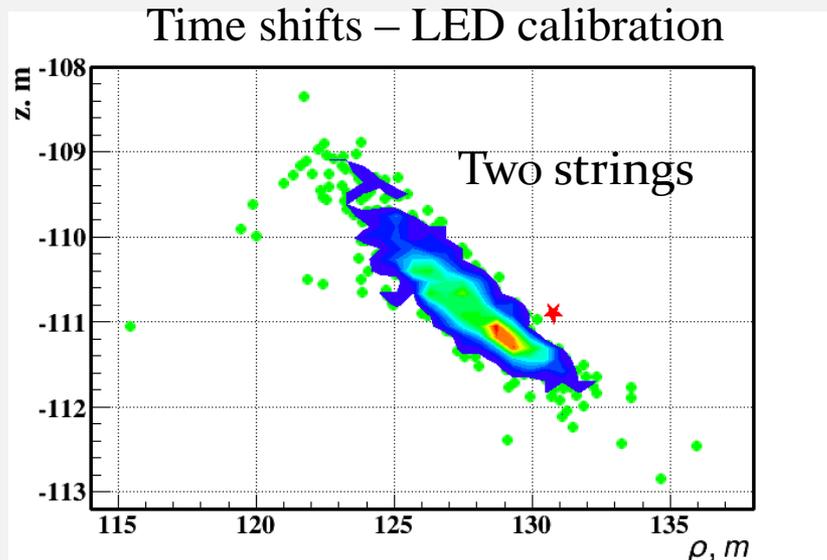
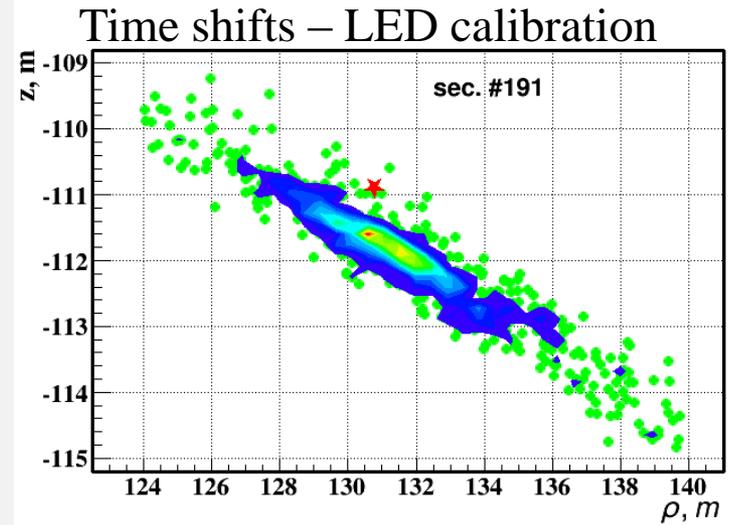


Distributions of reconstructed laser intensities: NT200 and Cluster

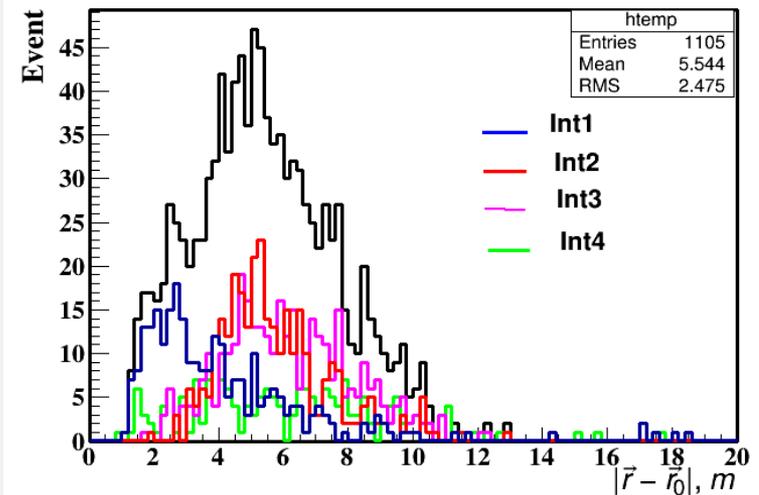
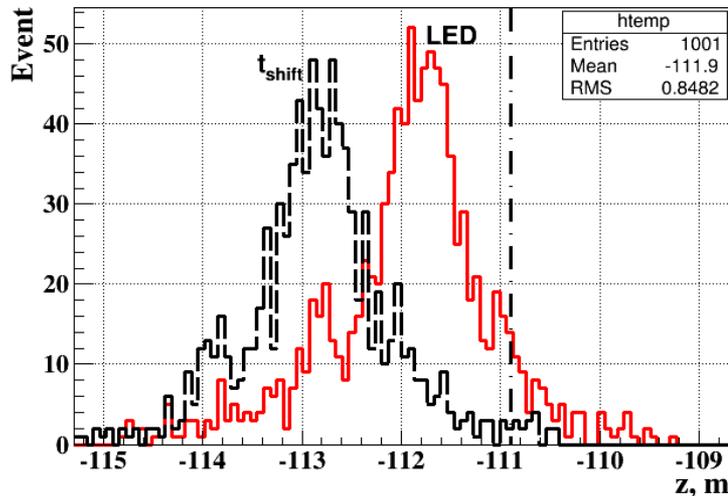
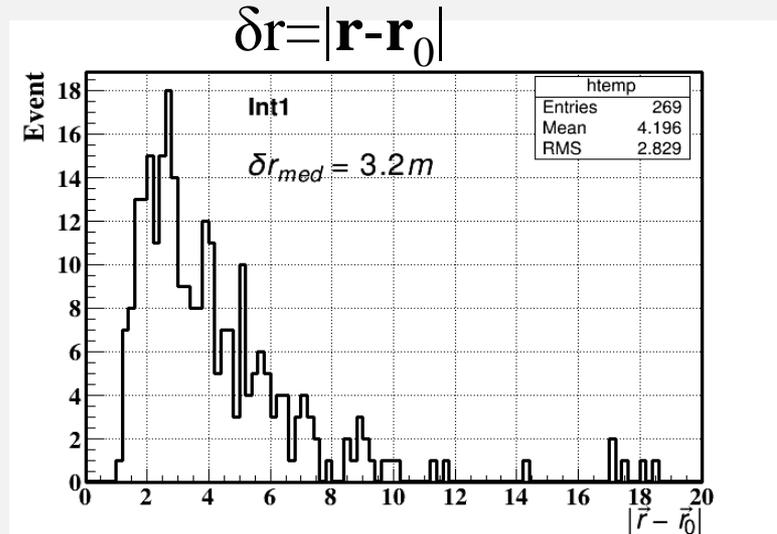
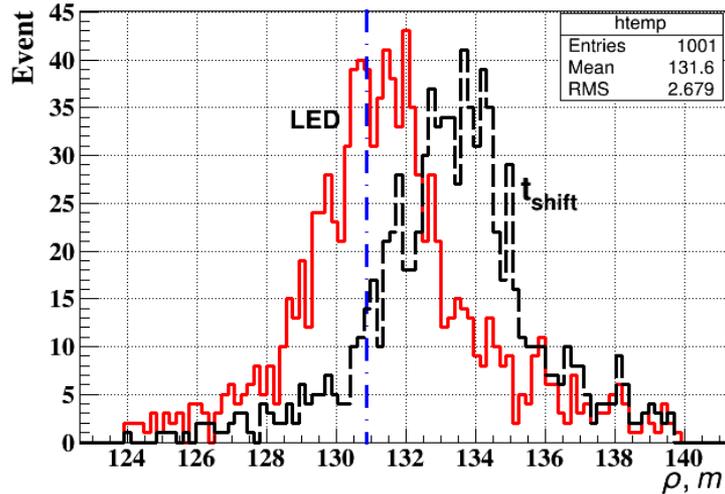
# Reconstruction of laser-light source position



Laser and OMs coordinates from data of acoustic positioning system



# Reconstruction of laser-light source position



# Atmospheric muons

Runs - (156 – 169)

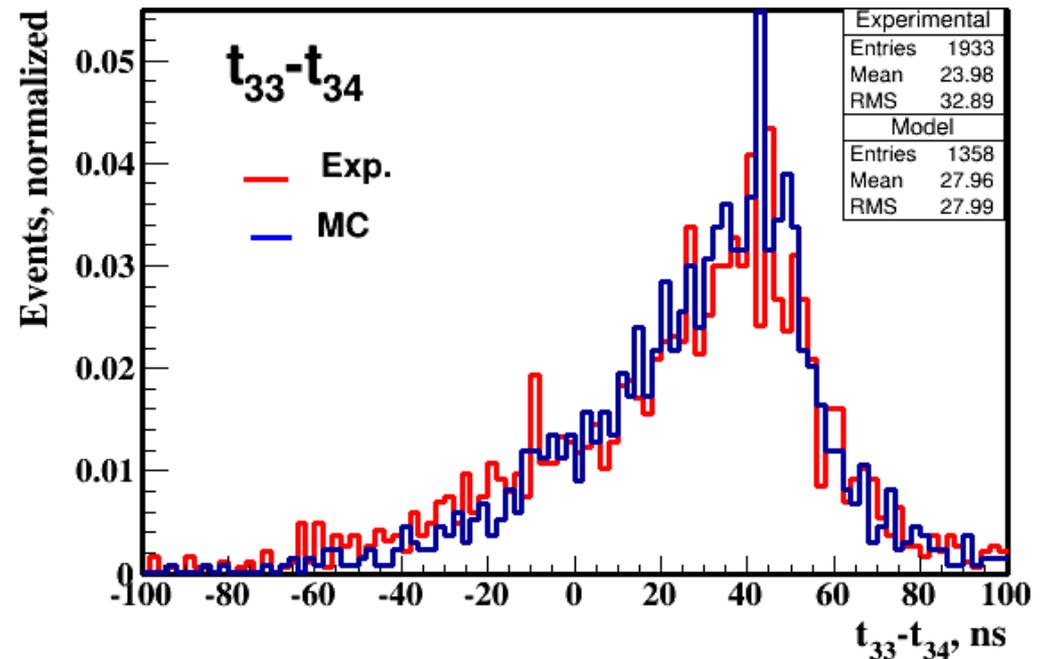
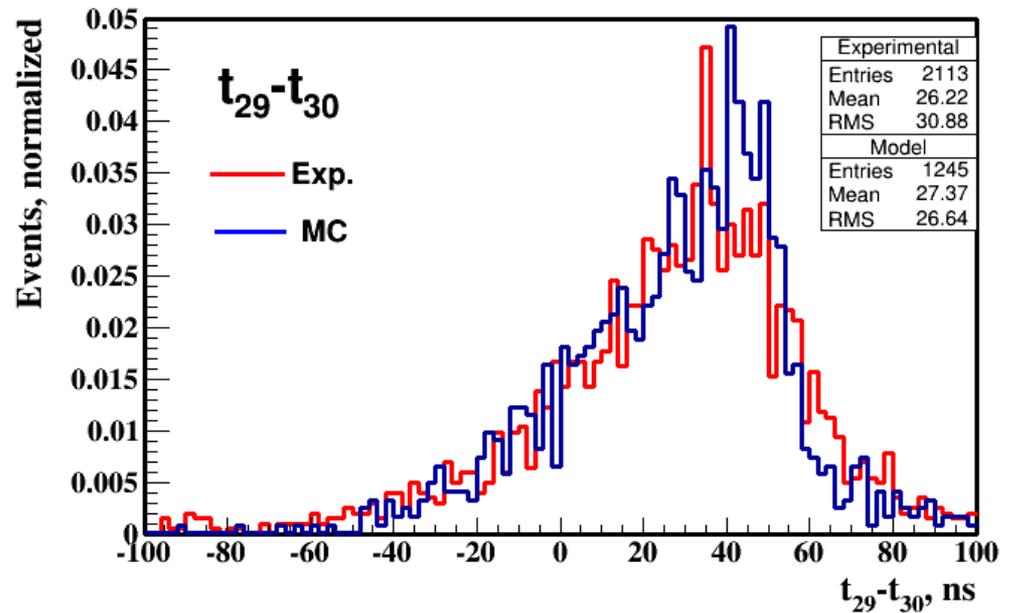
Statistics - 1707896 events

Trigger - 4 OMs /section

Selection –  $Q > 2$  ph.el.

LED – calibration

Data consistent with expectation



## FPGA XILINX Spartan 3 -> XILINX Spartan 6

### 1. ADC:

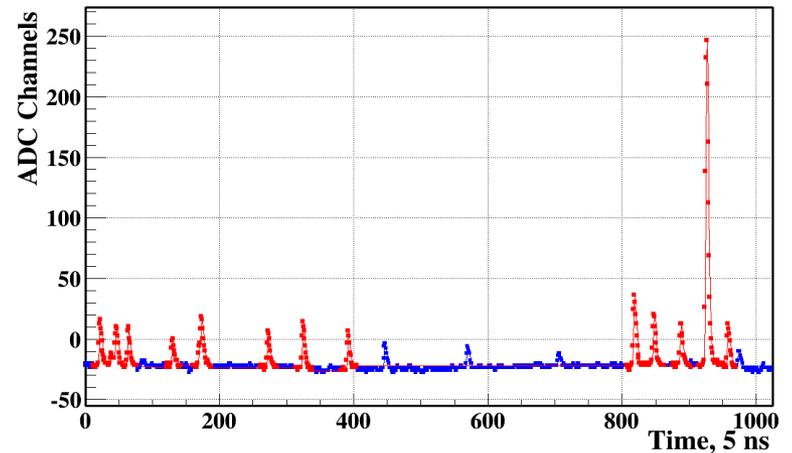
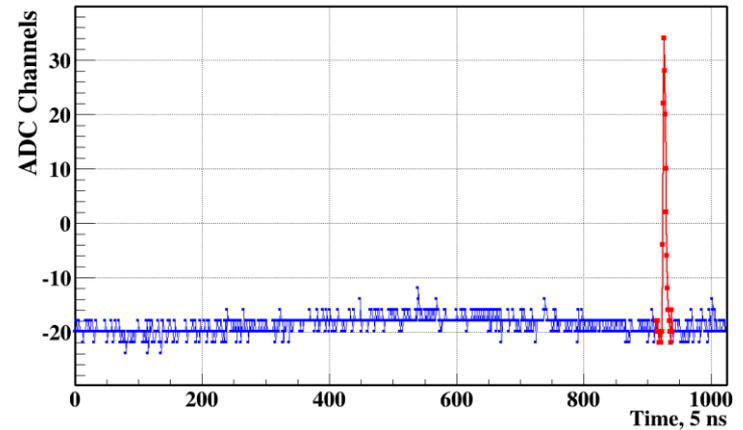
- Dead time minimization: Replacing of a single ADC data buffer for Spartan 3 (~1.5 ms dead time) with a double ADC buffer for Spartan 6
- Increasing the number of bins of the channel amplitude histograms: 250 mV -> 2 mV

### 2. Master:

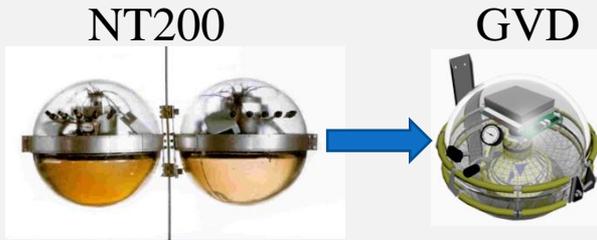
#### Increasing allowed trigger rate: 5-10Hz -> 50Hz

Trigger rate is limited by the data transmission rate from the strings to DAQ-center: 5-6 Mbit (Ethernet, shDSL modem, 1 km line length).

New firmware of the Master board: on-line data filtering. Cut the pulses from data frame and paste to output data stream. Rejection factor : 30-40



# Light background at 1000 – 1300 m depths

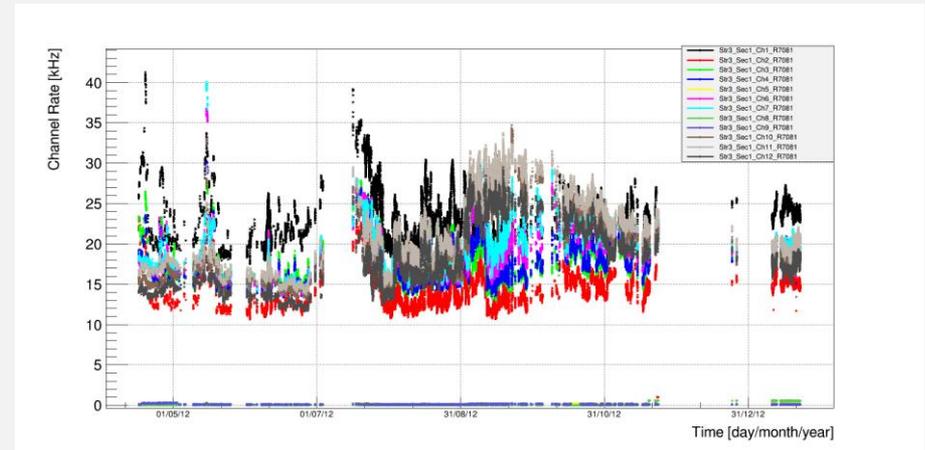


During 2011 – 2012 OMs counting rates were stable at a level of 15-30kHz

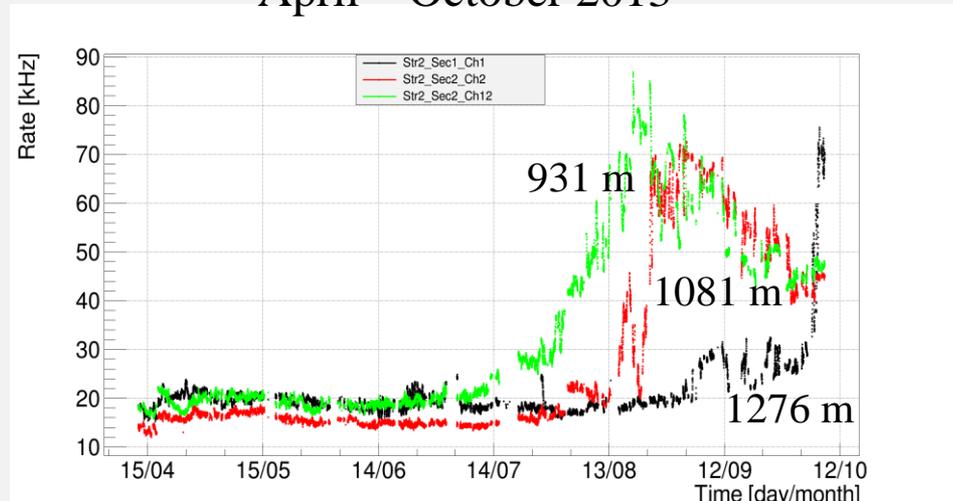
During 2013 counting rates rise from 15-10 kHz (April-June) up to 80 kHz (In July-September)

~200 m thick water layer with high background intensity sinking with velocity about of (6 -7) m/day

April 2012 – February 2013



April – October 2013

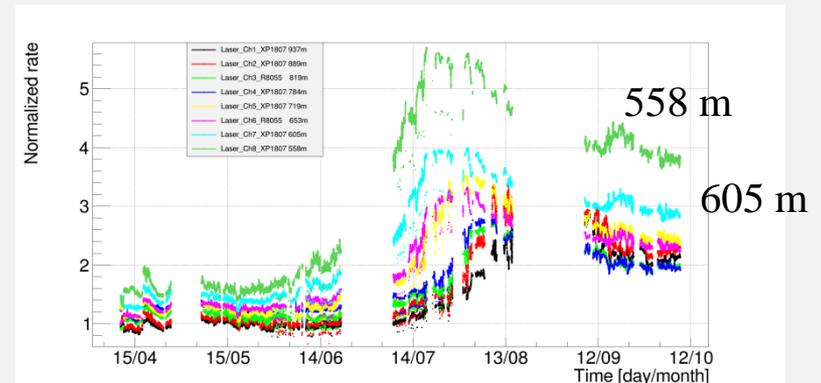
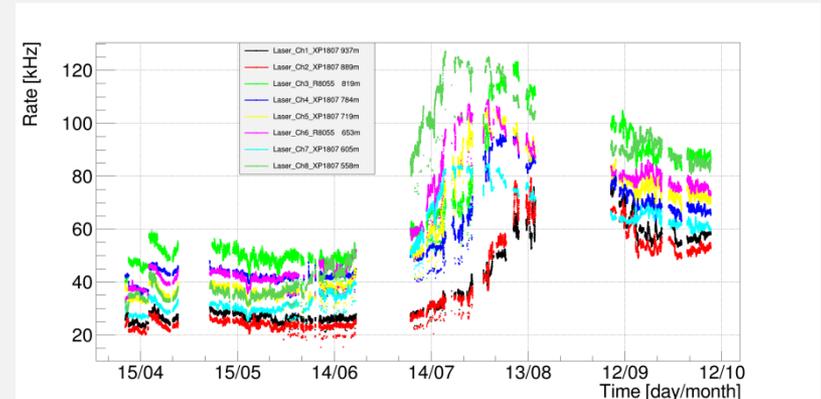


# Instrumentation string

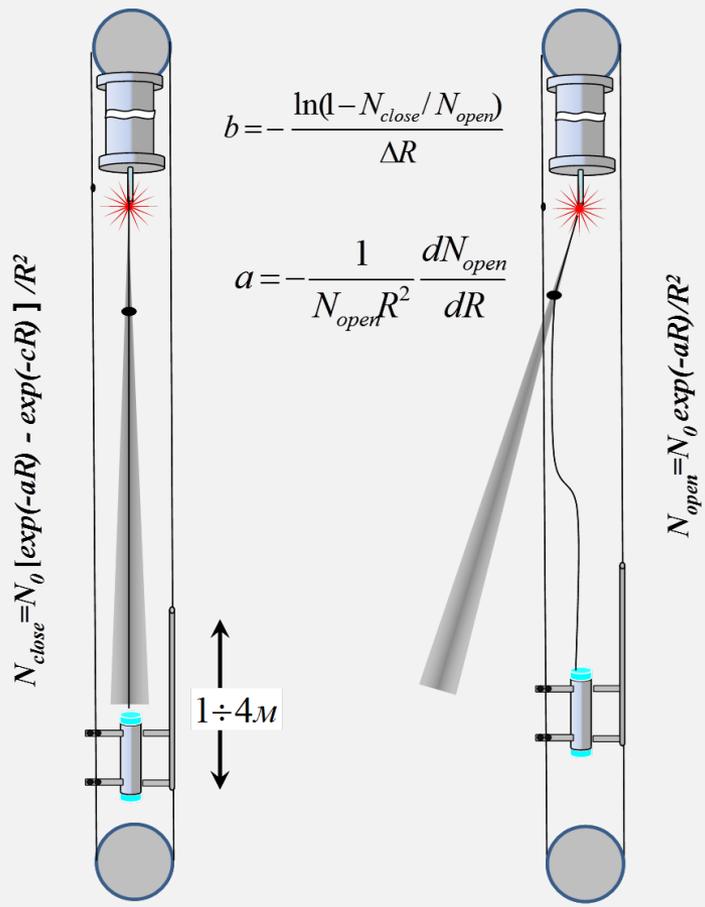
Depth – 588m – 937 m

## Temporal behaviour of light background

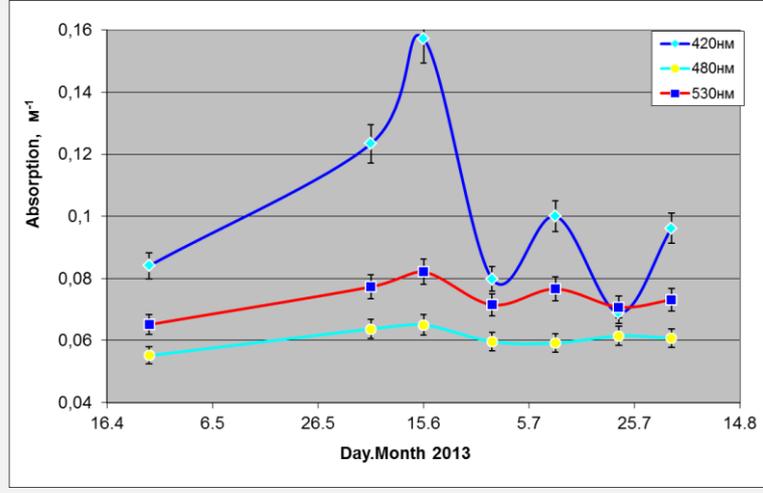
- April – June:
  - noise level increase on factor  $\sim 2$  with depth decreasing from 940 m to 600 m
- July – August: background increase on all depths due to sinking layer of water with high luminosity
- August – October: noise level decrease with time



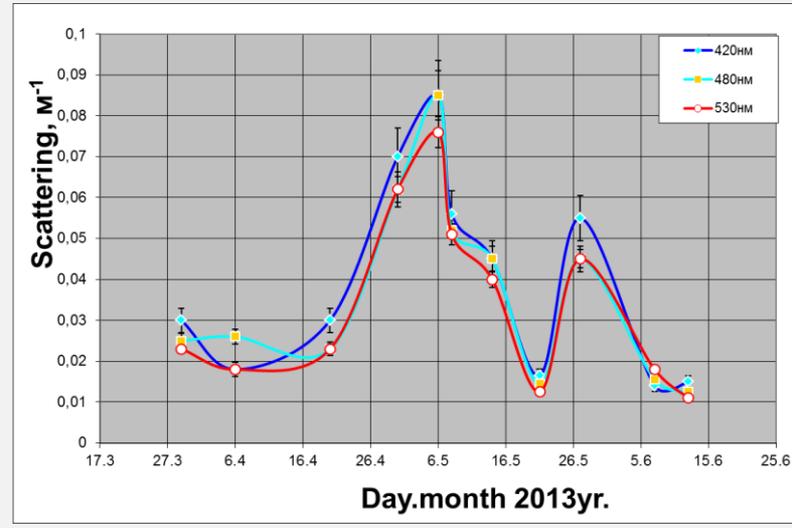
# Water optical properties: new device for in-situ measurements



## Absorption



## Scattering



# **Nearest plans**

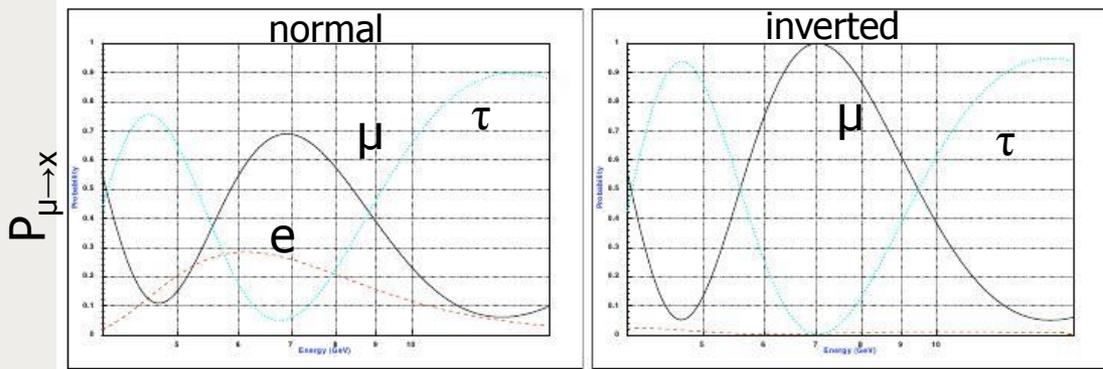
- 2013 – operation of the first stage of demonstration cluster, production and lab. tests of two new strings**
- 2014 - deployment and operation of 5 string array – the second stage of demonstration cluster, production and lab. tests of three new strings**
- 2015 – deployment and data taking with GVD demonstration cluster comprising 8 strings**

# Multi-megaton array with $\sim 1$ GeV threshold

(low energy phenomena - neutrino oscillations, dark matter ...)

- Atm. Neutrinos: energy – zenith angles distributions of muons and cascades
- Long Base Line Experiments: CERN-BAIKAL

F.Vissany et al., arXiv:1301.4577



	Fermilab	CERN	J-PARC
South Pole	11600	11800	11400
Sicily	<b>7800</b>	1230	9100
Baikal Lake	8700	<b>6300</b>	3300

Energy 6-8 GeV; distance 6000-8000 km;  
 $N^{NH}/N^{IH} \sim 0.7$  (30% difference);  
 For  $10^{20}$  p.o.t. @ Mton Volume  $N_{\mu} \sim 1000$  events

## Multi-Megaton low threshold array in Lake Baikal:

The same detection system as for GVD!

Configuration – 9 independent subarrays (heptagons)

OMs – 1500 – 3000;

Positioning precision during deployment < 1 m

Heptagon strings deflections due to water currents during year-exposition < 1m

These allow OM spacing  $\sim 3$  m (vert.); 7-10 m (hor.);

Reconstruction of energy and direction of secondary muons and cascades allows selection of events induced by neutrinos of all flavors.

